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A Vehicle Detection Model From Scratch Since No Labeled Data Is Provided. Instead, We Leverage Transfer Learning And Perform Inference On Our Dataset Using The 3D Deform Feb 3th, 2024
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2 Vehicle Position Estimation Algorithm .
2.1 Vehicle Dynamic Model . In This Study, A Bicycle Model, Which Approximates Both Right And Left Wheels As A Single Wheel, Was Used As The Vehicle Dynamic Model, As Shown In Fig. 1. Eq. (1) Shows The Equation Of Motion Of This Vehicle Dynamic Model With Three Degrees Of Apr 3th, 2024
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Kalman Filter: The State Update Equation And Measurement Equation Are Given By: $() () 0.9 (1) () Z X Vt X T X T W T$ (5) And The Noise Sources Are White Gaussian Noise Sequences With Zero Mean. The Process Noise Covariance Q Is 0.1997 Apr 1th, 2024
Contact State

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