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When We Studied Linear Systems (the Case Of Two

Negative Eigenvalues). To Study The Behavior Of A Nonlinear Dynamical System Near An Equilibrium Point, We Can Linearize The System. We Will First Explain This Approach In General And Then Return To The Example Discussed Above. Consider A System $(\dot{x}, \dot{y}) = f(x, y)$ $\dot{x} = f(x, y)$ $\dot{y} = g(x, y)$ = Feb 10th, 2024

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Not Fall On The Line; Second, The Line Does Not Cross The Y-axis At Zero, And We Would Expect It To - After

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The Previous Equations Define The RTD Resistance As A Function Of Its Temperature, $R_{RTD}(t)$. However, To Implement An RTD Sensor Interfacing Circuit, The RTD Temperature Must Be Determined, Instead, As A Function Of Its Resistance, $T_{RTD}(r)$. This May Be Less Straightforward, Given The Mar 24th, 2024

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