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[17] Ian R. Manchester, Uwe Mettin, Fumiya Iida, And Russ Tedrake. Stable Dynamic Walking Over Uneven Terrain. The International Journal Of Robotics Research (IJRR), 30(3):265-279, January 24 2011. [18] Alexander Shkolnik, Michael Levashov, Ian R. Manchester, And Russ Tedrake. Bounding On Rough Terrain With The Littledog Robot. Feb 9th, 2024

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