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Nonlinear Systems And Control Lecture # 7 Stability Of ...

Theorem: The Equilibrium Point $X = 0$ Of $X' = Ax$ Is Stable If And Only If All Eigenvalues Of A Satisfy $\text{Re}[\lambda_i] \leq 0$ And For Every Eigenvalue With $\text{Re}[\lambda_i] = 0$ And Algebraic Multiplicity $Q_i \geq 2$, $\text{Rank}(A - \lambda_i I) = N - Q_i$, Where N Is The Dimension Of X . The Equilibrium Point $X = 0$ Is Globally Asymptotically Stable If And Only If All Eigenvalues Of A Satisfy $\text{Re}[\lambda_i] < 0$

Nonlinear Systems And Linearization

When We Studied Linear Systems (the Case Of Two Negative Eigenvalues). To Study The Behavior Of A Nonlinear Dynamical System Near An Equilibrium Point, We Can Linearize The System. We Will First Explain This Approach In General And Then Return To The Example Discussed Above. Consider A System $(\dot{x}, \dot{y}) = F(x, y)$ $(\dot{x}, \dot{y}) = F(x, y)$ Apr 10th, 2024

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Required System Dynamics, Which In Turn Allows Us To Establish Regions Of Stability. To Summarize, The Main Contributions Of This Work Are As Follows: We Formulate The Searching Of Safe Regions For Arbitrary Nonlinear Dynamical Systems As A Convex Optimization Problem, By Dealing With A Scalar Function Of States. Mar 21th, 2024

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