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Ros\_control: A Generic And Simple Control Framework For ROS Sachin Chitta<sup>9, 11</sup>, Eitan Marder-Eppstein<sup>1</sup>, Wim Meeussen<sup>1</sup>, Vijay Pradeep<sup>1</sup>, Adolfo Rodríguez Tsouroukdissian<sup>12, 2</sup>, Jonathan Bohren<sup>8, 10</sup>, David Coleman<sup>3, 11</sup>, Bence Magyar<sup>4, 2</sup>, Gennaro Raiola<sup>5, 2</sup>, Mathias Lüdtkke<sup>6</sup>, And Enrique Fernandez Perdomo<sup>7, 2</sup> 1 HiDOF, Inc. (at The Time Of This Work) 2 PAL Robotics (at The Time Of This Work) 3 PickNik Jun 1th, 2024  
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Concept Mapping Is Often Confused With Mind Mapping (Ahlberg, 1993, 2004; Slotte & Lonka, 1999). However, Unlike Mind Mapping, Concept Mapping Is More Structured, And Less Pictorial In Nature. Jan 1th, 2024.

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Simultaneous Localization And Mapping (SLAM) Method For A Robot With An Omnidirectional Camera. In The EKF Part, We Employ A Sequential Process That Utilizes Features In Turn For Updating The Robot Pose Estimate. This Approach Enables Us To Efficiently Reduce The Computational Complexity And Predict Feature Search Regions. Jun 1th, 2024

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