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Flechtner 4,5 1 School Of Geosciences, China University Of Petroleum (East China), Qingdao 266580, China; Kfhe@upc.edu.cn Jan 3th, 2024

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Simulated By MATLAB Software (Mittal And Nagrath, 2003). (a) (b) Fig. 2: Link Kinematic Of Right Arm In Position 1 (a) (b) Fig. 3: Link Kinematic Of Right Arm In Position 2 In Fig. 2a It Shows Exoskeleton Suit For Right Arm With Joint Angle θz1 And With Link Twist αz1 In Fig. 2b. The Angle θz0 Is Attached With Human Body. Jul 2th, 2024

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