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Model Of Segway PT Is Obtained. By Combining These Two Models A Comprehensive Model Is Obtained In Which, The Input Is DC Motor Voltage And The Output Is The Physical Pose Of Segway PT And This Model Is Used For Controller Design In Section 3. [3],[5],[6]. 2.1. Linear Model Of A DC Motor 1th, 2024

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J The Algorithm Below Is Given In [8]. A) Start With An Estimate M, With F(x), The Optimum Value Off, 2 M,, I.e., Start With An Optimistic Guess For M,. Leti= 1. B) Minimize $F_1(X)$, And Let Xi Be The Resulting Solution. Define $F_1(X)$ = $F_2(X)$ = $F_3(X)$ =

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